

Tools

Image Processing Graphics & Calculations Pointlist String-buffer GUI

Statistic counters Input & Output Program flow Other

The number of VIMOS tools is ever increasing. Since the software is running on different hardware plattforms, not all tools are availlable everywhere. The following table is intended to give a quick overview. Some of the tools have more then one function. If you seek for something, it might not be found in the name of the tool, but in the short description given here.

While you can call your own software modules from VIMOS, it would still be good, if you would call when you miss a tool with a given functionality. Probably it is on our list of tools to be added, so maybe we can prepare it for your application.

Most tools are available for ALL cameras. Some of the most powerfull tools need to many resources. So they are available only on the TI-CAMs, which are the VC-cameras having VC20xx designators. Then there are tools, that only draw on the screen. Such tools are without use on sensors without a video-output and are therefore labled as available only on CAMs (cameras). Finally there are tools that work with special hardware features of the Sensors or even more specific, the M40.

For more information please download the 'Tools description' document.

| | Image processing | Cameras | Description |
|------------------|--|---|---|
| | Median filter 3x3 Convolution filter Barcode reader Rectangle test Circle test Color pixel counter Contour Correlation init Correlation exec Edge detection Fast edge detection Edge detection 2 Find blobs Image area Image projection Light balance Percent threshold OCR tool | ALL | good to filter noise out of images many uses, i.e. sharpening, softening, edge enhancement reads Code 39 and Interleaved 2 of 5, ask for others pls. relation bright / dark within an area (threshold, rotatable) relation bright / dark within a circular area multiuse color-segmentation or grayscale texture analysis subpixel-precise contour-following store a pattern for later selection by the Correlation exec normalized correlation - searching by matching patterns high-quality filtered single-line edge-detector fast version of the edge-detector, only 0, 45, 90 degrees multi-line, fast, threshold based edge-detector image binarization (2 thresholds) and object segmentation Copy,And,Or,Xor,Not,Add,Sub,Min,Max,Pyramid,Subsample horizontal or vertical projection: average brightness checks the average brightness - detects illumination failure threshold that follows brightness, also average brightness simple OCR, teachable, size independent, rotatable |
| 0 6 8 8 | Object recognition ini Object recognition exec Load image area Save image area | TI-CAMS TI-CAMS ALL ALL | teach an object to recognize later recognize objects, even zoomed, rotated and occluded loads part of an image from flash, like patterns or masks saves part of an image, like error-images or patterns |
| | Graphics & Calculations | Cameras | Description |
| ⊠ T ₩ ≪ | Marker Text box Distance Angle Calculator | ALL CAMS ALL ALL ALL | draws a cross of the size you wish at a point you specify text output distance measurment between points and / or lines angle measurement calculations with tool-results |

| Make point ALL creates a point at a location specified by two values Convert point ALL creates a point at a location specified by two values creates a point at a location specified by two values creates a point at a location specified by two values creates a point at a location specified by two values creates a point at a location specified by two values creates a point at a location specified by two values creates a point at a location specified by two values creates a point at a location specified by two values creates a point at a location specified by two values creates a point at a location specified by two values creates a point at a location specified by two values creates values out of the X and Y coordinates of a point draws a line given by a point and an angle draws a line through two points and returns the angle | \pm_{Δ} | Tolerance | ALL | checks if a value is within a given range |
|--|----------------|-----------------------|------|---|
| Convert point ✓ Infinite line ✓ 2-point infinite line ALL creates values out of the X and Y coordinates of a point draws a line given by a point and an angle draws a line through two points and returns the angle | *** | Midpoint | ALL | creates a point on the line between 2 pts. between or behind |
| Infinite line ALL draws a line given by a point and an angle 2-point infinite line ALL draws a line given by a point and an angle draws a line through two points and returns the angle | X*× | Make point | ALL | creates a point at a location specified by two values |
| 2-point infinite line ALL draws a line through two points and returns the angle | ×+X | Convert point | ALL | creates values out of the X and Y coordinates of a point |
| | * | Infinite line | ALL | draws a line given by a point and an angle |
| Finite line CAMs draws a line between two points | * | 2-point infinite line | ALL | draws a line through two points and returns the angle |
| | ~ | Finite line | CAMs | draws a line between two points |
| Best line ALL approximates a best-fit line from up to 10 points, see also | BEST | Best line | ALL | approximates a best-fit line from up to 10 points, see also |
| | \times | Line-cross | ALL | returns the crossing point of two lines |
| Point-projection ALL returns the point on a line, that is closest to a given point | 1/2 | Point-projection | ALL | returns the point on a line, that is closest to a given point |
| Line across circle ALL returns the points where a line crosses a circle | Ø | Line across circle | ALL | returns the points where a line crosses a circle |
| | <u>, 199</u> | Tangent | ALL | returns closest, farest and the two tangential points |
| 2-point circle ALL draws a circle from center and point, gives the radius | (3) | 2-point circle | ALL | draws a circle from center and point, gives the radius |
| 3-point circle ALL draws a circle from 3 points, gives center, radius and area | Q | 3-point circle | ALL | draws a circle from 3 points, gives center, radius and area |
| Best circle ALL approximates a best-fit circle from up to 10 points, see also | € | Best circle | ALL | approximates a best-fit circle from up to 10 points, see also |
| | P | Circle-cross | ALL | finds the crossing points of two circles |
| Rectangle ALL draws a rectangle from center, angle and size, gives area | \otimes | Rectangle | ALL | draws a rectangle from center, angle and size, gives area |
| Coordinate system CAMs draws a coordinate system | + | Coordinate system | CAMs | draws a coordinate system |

| Pointlist | Cameras | Description |
|---|---|---|
| Load pointlist Save pointlist Set pointlist parameter Set pointlist item Get pointlist parameter Get pointlist item Get blob Sort pointlist Filter pointlist Display pointlist Generate line coordinates Generate circle coordinat. | ALL | loads a pointlist from flash, good for program-parameters saves a pointlist to flash-memory sets one of the 8 parameters of a part of the pointlist sets one element of the pointlist (point + 8 parameters) gets one of the 8 parameters from one element of the list gets one element of the pointlist (point + 8 parameters) gets the information of one blob object from the pointlist rearanges pointlist elements depending on one parameter copies part of the pointlist depending on one parameter more then one way to display points from the pointlist generates coordinates on a line in pointlist elements generates coordinates on a circle in pointlist elements |
| | | |

| Move & Rotate pointlist Get grayvalues from pts. Pointlist median filter Pointlist edge-detection Pointlist distance Pointlist angle Pointlist Best-line Pointlist Best-circle Pointlist Hough-line/circle Contour matching Matching error filter Pointlist compare Fast pointlist compare | ALL ALL ALL ALL ALL ALL ALL TI-CAMS TI-CAMS ALL ALL ALL | displaces and rotates pointlist coordinates vs. point or line reads the grayvalue at point locations into a parameter filters a parameter sequence over a part of the pointlist detects edges on a parameter sequence fills a parameter sequence with the distance to a point or line fills a parameter sequence with the angle to a point approximates a best-fit line from pointlist points approximates a best-fit circle from pointlist points approximates a Hough line or circle from pointlist points very powerfull multi-contour object comparision, subpix errors filter for creating two-dimensional error-objects finds best matched position between lists, linear and circular same as above, but integer precision instead of floating pt. |
|--|---|---|
| String-buffer | Cameras | Description |
| Load string-buffer Save string-buffer Put character into buffer Get character from buffer Number to string String to number Show string Compare strings | ALL ALL ALL ALL ALL CAMS ALL | loads strings from flash - i.e. for the graphical user-interface saves strings to flash - i.e. from OCR, barcode, sets an element of the String-buffer gets an element of the String-buffer takes a value (result) and writes it as a sequence of numbers takes a sequence of numbers and returns a value (result) displays a string on the screen compares two strings |
| Graphical user-interface | Cameras | Description |
| ■ Window ■ Button ■ Edit / Text field ■ Radio-button ☑ Checkbox ➡ Spin / Combo | | draws a button draws an edit or text field draws a group of radio-buttons |

| Initialize GUI | TI-CAMs | initializes various properties of the GUI |
|--|---|--|
| Statistic counters | Cameras | Description |
| Reset counters to 0 Increment counter Decrement counter Set counter Save counters to flash | ALL ALL ALL ALL | resets one or all counters to zero increments a counter (+1) decrements a counter (-1) sets a counter to a given value saves all counters to flash, they are relodaded at power-up |
| Input / Output | Cameras | Description |
| Get I/Os Set I/Os Get I/O-box Set I/O-box Clean serial input queue Receive result Send result Receive string Send string Receive pointlist Send pointlist Receive image-area Send image-area | ALL | reads the state of the PLC-input-lines sets the state of the PLC-output-lines reads the state of the PLC-input-lines from an extension-box sets the state of the PLC-output-lines of an extension-box deletes the content of the serial input-buffer receives a result value via serial port sends a result value via serial port receives part of the string-buffer via serial port sends part of the string-buffer via serial port receives part of the pointlist via serial port sends part of the pointlist via serial port receives a rectangular area of the image via serial port sends a rectangular area of the image via serial port |
| Program flow | Cameras | Description |
| ☐ Cycle counter ☐ IF / ELSE / CASE ☐ GOTO ☐ LABEL ☐ Load user-program | ALL ALL ALL ALL | number of program executions - good for initializations enables conditional execution jumps to a label labels a place to jump to loads another user-program |

| Exec (external source) | ALL | executes an external exec-module (alien source) |
|------------------------|-----|--|
| ☑ Exit | ALL | exits the program to Edit-mode or operation system |

| Other Cameras | | Description |
|--|---|---|
| Zake picture Zake CMOS picture Copy picture Button & LED Pause / Wait Timer Delete file / Pack flash Free correlation pattern Select calibration set | ALL M40 ALL Sensors ALL ALL ALL ALL ALL | takes a new picture with given shutter and triggering takes a new picture of given size, shutter and triggering copies the entire image between frame & freeze buffers checks the button and sets the LEDs off the sensors M40,50 stops the execution for a given time or until a mouse-click returns elapsed time in hr:min:sec:ms - up to 10 timers deletes a file and does fast flash-packing deletes one of the patterns loaded with Correlation init activates one of the calibration sets |

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